

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

Claim 1 (previously presented): A seeding machine comprising:

a frame;

a wing frame is pivotally mounted to the frame so that it can be pivoted from a working configuration to a transport configuration;

a hopper for holding seed;

a pivot arm having a first end and a second end, the first end of the pivot arm is pivotally mounted to the wing frame, the pivot arm having a working position and a transport position;

a planting unit is mounted to the second end of the pivot arm, the planting unit comprises a seed meter, an auxiliary hopper and a furrow opener, when the pivot arm is in its working position the planting unit is in contact with the ground;

a flexible tube extends between the hopper and the auxiliary hopper of the planting unit for directing seed from the hopper to the planting unit;

when the wing frame is moved to its transport configuration, the pivot arm is moved to its transport position wherein the planting units are pivoted vertically.

Claim 2 (original): A seeding machine as defined by claim 1 wherein the pivot arm has an intermediate position between its working position and its transport position, whereby the ground engaging tool is no longer in contact with the ground.

Claim 3 (original): A seeding machine as defined by claim 2 wherein the first end of the pivot arm is pivotally coupled to the wing frame by a rock shaft having a bell crank, the rock shaft defining a first pivot axis about which the pivot arm is pivoted, a linear motor extends between the frame and the bell crank for rotating the rock shaft relative to the wing frame and thereby pivoting the pivot arm.

Claim 4 (original): A seeding machine as defined by claim 3 wherein the linear motor is a hydraulic cylinder.

B, Claim 5 (original): A seeding machine as defined by claim 1 wherein the planting unit is attached to the pivot arm by a parallel linkage that allows the planting unit to follow the ground independent of the pivot link when the pivot link is in its working position.
